

view\_frames Result  
Recorded at time: 1294762063.895

/map

/odom

/base\_footprint

Broadcaster: /fake\_localization  
Average rate: 100.513 Hz  
Most recent transform: 1294761919.469 sec old  
Buffer length: 1.950 sec

Broadcaster: /gazebo  
Average rate: 100.510 Hz  
Most recent transform: 1294761919.449 sec old  
Buffer length: 1.960 sec

Broadcaster: /robot\_state\_publisher  
Average rate: 50.515 Hz  
Most recent transform: 1294761919.469 sec old  
Buffer length: 1.940 sec

Broadcaster: /robot\_state\_publisher  
Average rate: 50.515 Hz  
Most recent transform: 1294761919.469 sec old  
Buffer length: 1.940 sec

Broadcaster: /robot\_state\_publisher  
Average rate: 50.515 Hz  
Most recent transform: 1294761919.469 sec old  
Buffer length: 1.940 sec

Broadcaster: /robot\_state\_publisher  
Average rate: 50.515 Hz  
Most recent transform: 1294761919.469 sec old  
Buffer length: 1.940 sec

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Average rate: 50.515 Hz  
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Average rate: 50.515 Hz  
Most recent transform: 1294761919.469 sec old  
Buffer length: 1.940 sec

/base\_caster\_box\_link

/base\_caster\_support\_link

/base\_link

/base\_link\_left\_motor\_link

/base\_link\_left\_wheel\_link

/base\_link\_right\_motor\_link

/base\_link\_right\_wheel\_link

/base\_scan\_link

/base\_top\_link

/caster\_wheel\_link

/computer\_link

/laser\_base\_link